

Welcome

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Welcome to the 2nd day of the interACT Virtual Final Event!

We are very excited to be presenting further results of our project today.







Agenda for today

Time	Topic
Opening session	า
13:00-13:05	Welcome
	Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany
13:05-13:15	"interACT – the vision of automated vehicles in mixed traffic" (Summary of Day I)
10.15.10.05	Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany
13:15-13:35	Keynote Mr .Tom Alkim, Policy Officer Connected & Automated driving at the European Commission, Directorate General Research & Innovation





Agenda for today

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13:35-15:40	·
The implementa	tion and evaluation of the interACT research:
evaluating the in	Human-Machine interaction, implementing the demonstrator vehicles and nterACT solutions
Moderators: Mrs.	Anna Schieben, DLR e.V. Germany Mrs. Natasha Merat, ITS Leeds, UK
13:35-14:05	"Developing interaction strategies and novel HMI concepts"
	Mr. Marc Kaup, HELLA, Germany Mr. Florian Weber, BMW, Germany
14:05 –14:15	Q&As
14:15-14:35	"Integration and technical Testing of the interACT demonstrator vehicles" Dr. Fabio Tango, CRF, Italy
14:35-14:45	Q&As
14:45-15:20	"Testing the interACT solutions: Methodologies and results for evaluation and impact assessment Dr. Yee Mun Lee, ITS Leeds, UK
15:20-15:30	Q&As
Closing session	
15:30-15:40	Wrap up of Day II and Conclusions of the project
	Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany





Virtual Final Event

interACT The vision of automated vehicles in mixed traffic Summary of Day 1

Anna Schieben

DLR e.V.

19 June 2020





Project facts

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• **Programme:** EU/H2020-**ART04** - Safety and enduser acceptance aspects of road automation in the transition period

• **Duration**: 36 months

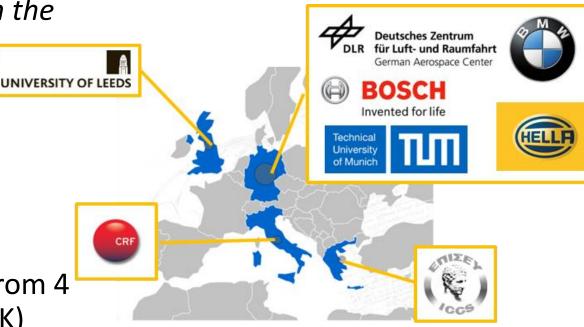
Period: May 2017 – April 2020 (Sept. 2020)

• **EU Funding**: 5.527.581 €

Coordinator: Anna Schieben, DLR

• Partners: 8 industrial and academic partners from 4 European countries (Germany, Italy, Greece, UK)

• US - EU twinning project: AVIntent (NHTSA)







Integrating automated vehicles in mixed traffic

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Situation Today







Future situation: Automated vehicles in mixed traffic environments





5th Objective

Methodology for assessing the quality of interaction





The challenge



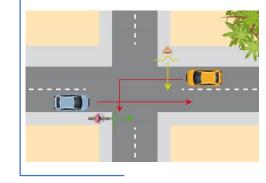
1st Objective

Psychological models



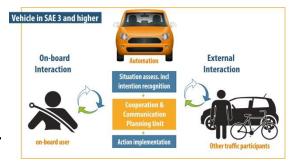
4th Objective Novel HMI elements

Achieve a safe, highly accepted and efficient integration of Automated Vehicles in mixed traffic environment



3rd Objective

CCPU & safety layer



2nd Objective

Intention recognition & behavioural predictions

5th Objective

Methodology for assessing the quality of interaction





The challenge



1st Objective

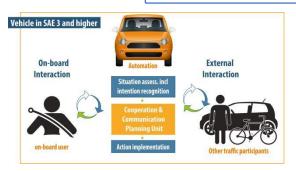
Psychological models

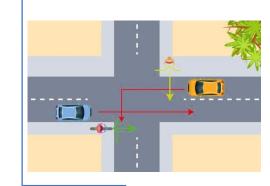


4th Objective **Novel HMI** elements



Achieve a safe, highly accepted and efficient integration of Automated Vehicles in mixed traffic environment





2nd Objective

Intention recognition & behavioural predictions

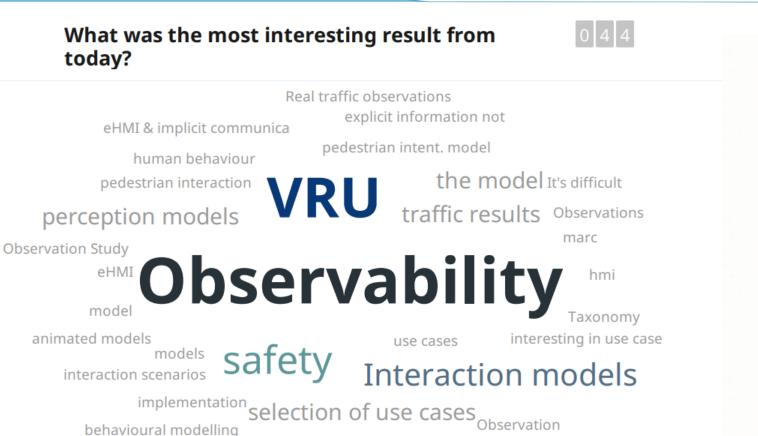
3rd Objective

CCPU & safety layer



Your highlights from yesterday

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Definition of interaction

interaction modelling Neurocognitive Models

5th Objective

Methodology for assessing the quality of interaction





The challenge

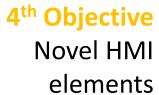


1st Objective

Psychological models









3rd Objective CCPU & safety layer

Vehicle in SAE 3 and higher On-board Interaction

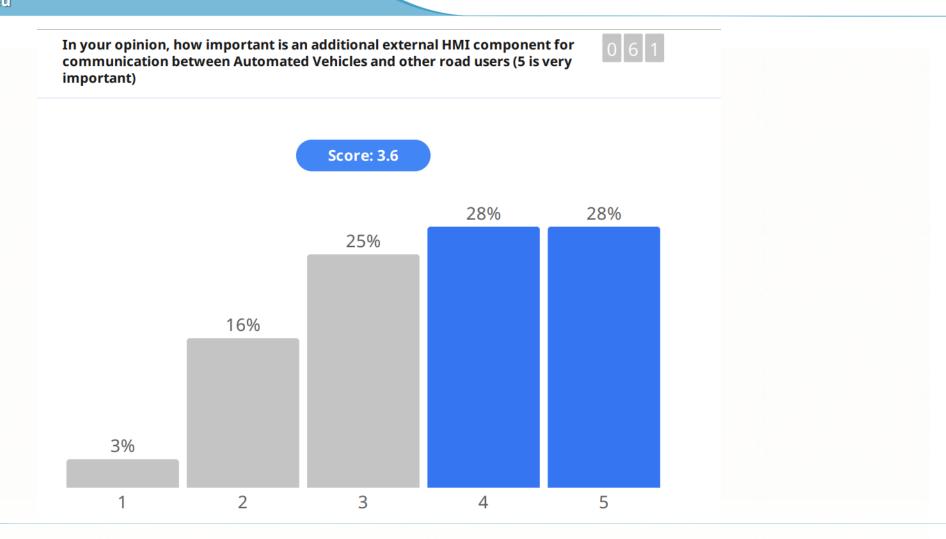
External

2nd Objective

Intention recognition & behavioural predictions



Poll questions







Poll questions







We hope you enjoy the 2nd day!

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Anna Schieben
Project Coordinator
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