

## Welcome

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## Welcome to the interACT Virtual Final Event!

We are very excited to be presenting the results of our project.







# Agenda for today

Time	Topic
Opening sessio	n
13:00-13:10	Welcome Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany
13:10-13:20	"interACT – the vision of automated vehicles in mixed traffic"  Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany





# Agenda for today

13:20-14:50 The basis for the interACT developments: Defining scenarios, observing real traffic & programming the vehicle automation Moderators: Mrs. Anna Schieben, DLR e.V. Germany   Mrs. Natasha Merat, ITS Leeds, UK		
13:20-13:40	"The interACT scenarios – defining and documenting essential urban scenarios for the development and evaluation of interACT solutions"	
	Mr. Marc Wilbrink, Senior researcher, DLR e.V., Germany	
13:40-13:50	Q&As	
13:50-14:10	"Observing human interaction in real traffic – what we learned for interACT"  Mr. André Dietrich, Senior researcher, Technical University Munich, Germany	
14:10-14:20	Q&As	
14:20-14:40	"From situation awareness to cooperation and communication planning of automated vehicles for their safer integration in mixed traffic: a modular approach"  Giorgos Drainakis, Senior Researcher, ICCS, Greece	
14:40-14:50	Q&As	
Closing session		
14:50-15:00	Wrap up of Day I and preview of Day II  Mrs. Anna Schieben, DLR e.V. Germany   Mrs. Natasha Merat, ITS Leeds, UK	





# Agenda for tomorrow

Time	Topic	
Opening session		
13:00-13:05	Welcome	
	Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany	
13:05-13:15	"interACT – the vision of automated vehicles in mixed traffic"  (Summary of Day I)  Mrs. Appl. Schieben, Coordinater of interACT Brainet, DI B o V. Cormony	
	Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany	
13:15-13:35	Keynote  Mr .Tom Alkim, Policy Officer Connected & Automated driving at the European Commission, Directorate General Research & Innovation	





# Agenda for tomorrow

13:35-15:40 The implementation and evaluation of the interACT research: Developing the Human-Machine interaction, implementing the demonstrator vehicles and evaluating the interACT solutions		
Moderators: Mrs. Anna Schieben, DLR e.V. Germany   Mrs. Natasha Merat, ITS Leeds, UK		
13:35-14:05	"Developing interaction strategies and novel HMI concepts"  Mr. Marc Kaup, HELLA, Germany   Mr. Florian Weber, BMW, Germany	
14:05 –14:15	Q&As	
14:15-14:35	"Integration and technical Testing of the interACT demonstrator vehicles"  Dr. Fabio Tango, CRF, Italy	
14:35-14:45	Q&As	
14:45-15:20	"Testing the interACT solutions: Methodologies and results for evaluation and impact assessment Dr. Yee Mun Lee, ITS Leeds, UK	
15:20-15:30	Q&As	
Closing session		
15:30-15:40	Wrap up of Day II and Conclusions of the project  Mrs. Anna Schieben, Coordinator of interACT Project, DLR e.V., Germany	





# **Poll questions**

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Hello and Welcome to the interACT event! Please answer the following question: What type of organisation do you represent (e.g. Research/Industry/Government etc.)



**European Commission** 

 $\mathsf{TUM}_\mathsf{DLR} Industry_\mathsf{Centro\ Ricerche\ Fiat}$ 

SME



University OEM

Academic Research
Research (University)





# **Poll questions**

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### Which country are you calling from?



India Turkey Switzerland
United States UK us Austria America

Canada

Greece Germany

pain

Netherlands Italy Sweden Japan Norway United Kingdom

Boston, Massachusetts





# **Poll questions**

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What is your main field of expertise? (human factors, design, sales, sensors, etc.)



Computer Science in VR

**Evaluation & Validation** 

Humanising autonomy

Control System motion planning

Neurocognitive psychology

R&D automated vehicles societal lighting

**HMT**Traffic safety

economics

Cognitive Science

# **Human Factors**

data science policy vehicle lighting

psychology Simulation

Software

Mobile communication

Transportation Safety

V2X Communication Systems Engineering

Computer Vision and ML

Human Factors/design





## Virtual Final Event

# interACT – the vision of automated vehicles in mixed traffic Project overview

Anna Schieben

DLR e.V.

18 June 2020





# **Project facts**

#### www.interact-roadautomation.eu

• **Programme:** EU/H2020-**ART04** - Safety and enduser acceptance aspects of road automation in the transition period

• **Duration**: 36 months

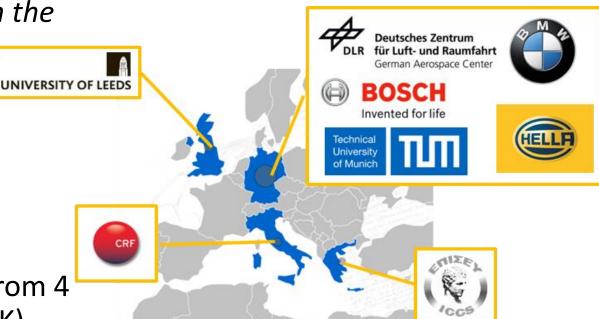
Period: May 2017 – April 2020 (Sept. 2020)

• **EU Funding**: 5.527.581 €

Coordinator: Anna Schieben, DLR

• Partners: 8 industrial and academic partners from 4 European countries (Germany, Italy, Greece, UK)

• US - EU twinning project: AVIntent (NHTSA)





# Integrating automated vehicles in mixed traffic

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### **Situation Today**







### Future situation: Automated vehicles in mixed traffic environments







# Challenges of interACT

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## The interACT project addressed the following challenges:

- Safe integration of AVs (SAE level 3 and above) into complex, mixed traffic environments
- Solutions for expectation-conforming interaction of Automated Vehicles (AV) with other road users and on-board users
- Increase in user acceptance and ease-of use by appropriate AV design
- Increase the overall safety and reliability of AVs in mixed traffic environments



### 5<sup>th</sup> Objective

Methodology for assessing the quality of interaction





The challenge



1<sup>st</sup> Objective

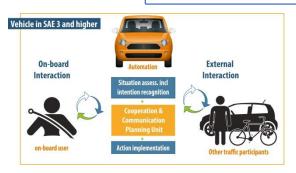
Psychological models

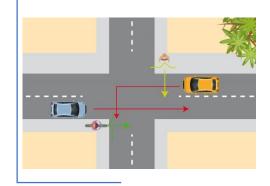


**4<sup>th</sup> Objective Novel HMI** elements



Achieve a safe, highly accepted and efficient integration of Automated Vehicles in mixed traffic environment





**2<sup>nd</sup> Objective** 

Intention recognition & behavioural predictions

3<sup>rd</sup> Objective

CCPU & safety layer

## 5<sup>th</sup> Objective

Methodology for assessing the quality of interaction





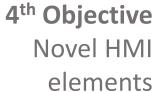
The challenge



1<sup>st</sup> Objective

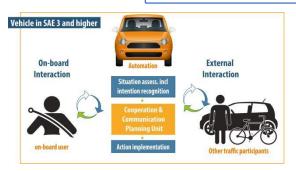
Psychological models

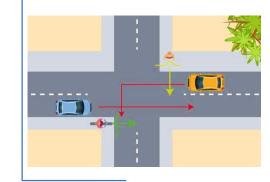






Achieve a safe, highly accepted and efficient integration of Automated Vehicles in mixed traffic environment





## **2<sup>nd</sup> Objective**

Intention recognition & behavioural predictions

**3rd Objective** 

CCPU & safety layer

## **5<sup>th</sup> Objective**

Methodology for assessing the quality of interaction





The challenge

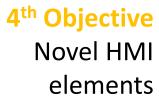


1<sup>st</sup> Objective

Psychological models

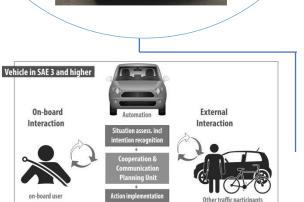


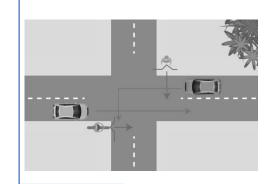






3<sup>rd</sup> Objective CCPU & safety layer





2<sup>nd</sup> Objective Intention recognition & behavioural predictions



## We hope you enjoy the meeting!

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